| 1 | My name is Eric Silverman, and I am a Defense Contractor working on a project for the US Army. What I am going to discuss is the Military's use of Python for modeling battlefield scenarios. I work out in the New Mexico desert at a secure military installation on classified projects. I mention that, so that you understand that what I'm going to be showing is generalized and very watered down. I apologize ahead of time if you're underwhelmed by the examples your about to see. | <section-header><section-header><section-header><section-header><section-header><section-header><text></text></section-header></section-header></section-header></section-header></section-header></section-header> |
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| 2 | I am one of many people who support the Army's Training and Doctrine Command, which is known as TRADOC. More specifically, we work for TRADOC's Analysis Center, or TRAC; which is the Army's research and analysis arm. Contrary to popular belief, the Army puts a lot of effort into research and analysis before spending millions, if not billions, of tax payers' dollars on new weapons, vehicles, and equipment. The work that is concerned with the analysis of Advanced Concepts and Requirements is done by the analyst at TRAC. | U.S. Army: Research & Analysis We support the U.S. Army Training and Doctrine Command (TRADOC) Analysis Center (TRAC) Mission of TRAC: Provide relevant, credible analysis for informed decisions about the Army's most important and challenging issues. www.tradoc.army.mit |

| 3 | One of the ways that the Army conducts their analysis is with computer models. | ALATEC inc Comba | at Model | |
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| | Modeling a combat scenario always starts with | Known Data | Combat Model | End Results |
| | what we know. The nature of this data is based in physics or validated quantifiable data. For example, we know that based on the size, weight, and velocity of a projectile how far it will | | | |
| | fly within specific gravitational, atmospheric, and environmental conditions. | | TWEINTY ONE | |
| | The analysts build a scenario based on a specific | | / _ | |
| | battle situation, and feed in the known data. And, runs it through the model. | Physics Quantitative Data | Analytic Stochastic Closed Form | Reports & Briefing Material |
| | COMBATXX is the wargaming model that we support. It uses a sophisticated stochastic system | | | |
| | to analyze the interactions between agents on the | play board. COMBATXX | I is what's known as a C | losed Form |
| | model. That means that all the parameters and scr where Python comes in, but we'll talk about that ir | ipts need to be develop | | |
| | After the model completes its run through the scer users) study, evaluate, and scrutinize the gigabytes that are presented to decision makers. | | | |
| | I'm going to show you an example of a very simple | battle ALATEC | Scripted Behaviors | |
| | scenario. It's very simple because of the time limita | ation. A | - 1 - 1-1 | / |
| | complex battle scenario can't be easily explained in minutes. Also, I want to warn you ahead of time: T | | °° | 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 |
| | NOT HALO !!! No cool 3-D graphics here. The powe | r behind | | × |
| | COMBATXXI is the stochastic analysis engine. It def not graphical output. | initely is | | |
| | Our scenarios, without Python, use scripted – or st | | / | |
| behaviors. Every aspect of the scenario had to be known, planned out, and meticulously scripted. | | nown, | | |
| | The first element in a scenario is the terrain. This is | | | |
| representation of an urban terrain. There are roadways, buildings – the black blocks, and a city grid. Wh 2-dimensional, top-down view, we do play height but do not represent it visual. In this scenario, we have placed 7 entities – or, agents. Six total good guys in 2 units, blue represents fr forces; and 1 bad guy, red represents hostile forces. | | | d. While this is a | |
| | | ents friendly | | |
| | For scripted behaviors to work we need to: | | | |
| | First, script an engagement behavior with specified weapons and targets. | | | |
| | Second, lay down routes for all the movements, an | | | |
| | And finally, test the scenario to make sure that ever What's going to happen is, you'll see, the red guy f | | | |
| | Then, the good guys to the west are going to move | | | |
| | You'll notice that there are 2 blue routes, because | | | |

You'll notice that there are 2 blue routes, because in the Army we always outflank the enemy.

However, the bad guy is going to flee the scene, and gets away.

| 5 | (Watch scenario play out) | ALATECine Scripted Behaviors |
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| | At this point the good guys stop because there are no scripted behavior to tell them exactly what to do and when to do it. Obviously, there are some serious shortcomings to this approach. But, rather than talking about what scripted behaviors cannot do, I'll show you an example of how we can do a lot more with the same scenario and dynamic behaviors. | Hostile Engages Field Forces Hostile Evacuates to the North Support Unit Flank Hostile's Position Hostile has Escaped!!! |
| 6 | Setting up a scenario for dynamic behaviors requires us to add some objects, and remove others. We start out with the same number of good guys. However, we've added a new bad guy to the south. The new bad guy is a spotter; his job is to look for his enemy the good guys, and then relay their position to the shooter. We have no preplanned routes now. However, we can designate high risk areas; such as a main thoroughfare. Generally speaking, soldiers don't like to be out in the open when in hostile territory. So, in our scenarios we designate an area that we know the blue force will avoid, and let the entities create their own path to the objective area. | ALATEC |

| location, rather than a specific target.– Notice the waypoint marker. | ALATEC:: Cognitive Behaviors w/Python Image: Comparison of the stress of the shooter is firing at a their own route to the objective area; still using a flanking |
|--|---|
| 8And, they will start moving out. Because we have intelligent agents on the play board, they can stop moving. If, say for example, "intel" is received about a source of information that can be interrogated while in route. This is a simple example of why Python is such a valuable tool for us. Unlike with scripted behaviors, with Python and dynamic behaviors, we have to ability break a maneuver while an agent is in route to the objective. | ALATEC |

| 9 | The agents, with situational awareness, can stop | ALATECime Cognitive Behaviors w/Python |
|----|---|---|
| | and create a new dynamic route to the new objective. After the interrogation is complete, they will move onto their original objective location. | |
| 10 | We also apply reactive behaviors with Python to the bad guys. So, Instead of just fleeing a tactical site, our hostile entity can maintain its position until it feels threatened. The hostile entity escapes the area only after seeing that it is outnumbered by the approaching blue forces. Of course, we can continue this scenario with how the blue force might pursue an escaping enemy. But, I think you get the idea. | ALATECHE ALATECHE Cognitive Behaviors w/Python |
| 11 | Why is this relevant? I believe President Obama said it best last August, when he stated that much of our defense establishment is still focused on Cold War doctrine and weapons. The President went on to say: "Twenty years after the Cold War ended, this is simply irresponsible. " Now, scripted behaviors are great if we are fighting in trench-warfare circa World War I, or even for armored battalions that are executing a Pincer maneuver in the oil fields of Kuwait. But, Irregular Warfare against enemies with IEDs that adhere to no rules of engagement; that requires a computer model that is much more flexible, much more agile, and much more adaptive. What was needed was a model with a Jython API implementation. | ALATECINE Relevance Much of our defense establishment is focused on Cold War doctrine and weapons. "Twenty years after the Cold War ended, this is simply not unacceptable. It's irresponsible." President Obama (August 2009) The Question: How do we not fight our last war? The Answer: Python |

| 12 | COMBATXXI has that embedded Jython API that allows users to control movements and actions of "entities". Entities can be almost anything - a tank, truck, soldier, or civilian. Jython's features allow for quick creation and implementation of dynamic behaviors. Each entity carries its own global Jython namespace throughout the simulation - roughly equivalent to memory and situational awareness of a real life person. COMBATXXI has events that trigger, which start the entities' Jython scripts, and causes the entity to react, or behave, in a more realistic and dynamic manner. When one entity reacts to a trigger, that entity's reaction may trigger another entity's behavior, resulting in a cascading effect across the entire scenario. | ALATECINE Jython Implementation COMBATXXI is developed with Java, and has an embedded Jython API Jython's features allow for quick creation and implementation of dynamic behaviors Each entity carries its own global Jython namespace throughout the simulation COMBATXXI has event triggers, which starts the entities' Jython scripts |
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| 13 | Because Jython provides un-tethered access to all of the Python, Java, and COMBATXXI source code it is very powerful - and very dangerous. Essentially, the Jython API gives the users full access to all of the Getters and Setters for all the objects in the source code. To protect the source code objects, we have created wrapper classes that provide access to the Getters, and only a select few Setters. There is also a Functions Library .py file to provide the users with useful and time saving callable method. Using the encapsulated methods, users develop the dynamic behaviors by importing the .py files with the methods that have been developed for their use. | ALATECIN Jython Implementation Encapsulated Source Code |

| 4 Here is a simple example of how dynamic movement might be scripted with Python code. | ALATECIN: Example Code Snippet |
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| We import the Functions library on line 3. Our users are non-programmers, so simple to understand and callable methods are the way to go. Admittedly, this is not the most Pythonic way to get the job done. But, in the end we would rather have something our users can understand – and with any luck, we won't offend the OOP Gods too much. On line 5, using the "location" wrapper class, we much something our users can understand. | 1 # from the Functions Library class 2 # import the [is_Line-of-Sight_Between_Locations] method 3 from funcLibrary import isLOSBetweenLocations() 4 # from the location wrapper class get the entity's current location 5 locOfMe = location.getMyCurrentLocation() # locOfMe is an object 6 # test LOS east 5 meters at a time 7 distRange = 5 8 while noLOS != True: # using noLOS as a Boolean, loop until it is True 9 # create a temporary location offset true east, by the value in distRange 11 locTemp = locOfMe.newOffsetLocation(90, distRange): 2 # test to see if the two locations have line-of-sight 13 noLOS = isLOSBetweenLocations(locOfMe, locTemp) 14 distRange += 5 # increase the distance by 5 meters 15 # create location object that is the longest point with line-of-sight 16 locToMoveTo = locOfMe.newOffsetLocation(90, distRange-5) |
| breaks out of the loop. | 13, we test two points. When there is no line of sight, the code |
| | 5, we have access to all of the object's properties and et_Location. By calling it, we can istantiate a new object by se to be offsetted towards the new location. |
| methods. One of those methods might be new_Offs | et_Location. By calling it, we can istantiate a new object by ce to be offsetted towards the new location. ALATEC Internet Example Code Snippet 16 locToMoveTo = locOfMe.newOffsetLocation(180, distRange-5) 17 # use the command wrapper class to create a move order object 18 moveOrder = command.createMoveOrder() |
| methods. One of those methods might be new_Offs passing in two parameters; the direction and distance With a different wrapper class called "command" we create a new object called moveOrder on line | et_Location. By calling it, we can istantiate a new object by ce to be offsetted towards the new location. ALATEC MS Example Code Snippet 16 locToMoveTo = locOfMe.newOffsetLocation(180, distRange-5) 17 # use the command wrapper class to create a move order object |
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The entity uses the distance of the last successful line of sight test as the point to move to. An order is created and executed, then the entity moves to the new location.

| Something that has not been talked about yet is | |
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| who is creating the dynamic behaviors with Python. | |

For the most part, they are research analysts with very little programming experience. That being the case, a lot of support needs to be provided.

To start with, a very detailed user document was authored and is maintained on an internal wiki. Because the users are not experienced programmers javadoc style documentation won't do. Instead, the user docs include full descriptions, examples on how to use the code, and even screenshots.

ALATEC Workforce Implementation

- Complete Documentation for users, to include examples in code snippet
- · Hands-on training sessions in computer labs
- · Continual support for users

The development group created a training program that was about 3-workdays worth of hands-on training. It started out with very simple topics that covered basic Python syntax, and then moved on to more advanced topics like using databases and class files.

This training had full support from management, which allowed the developers ample time and resources to create the training program. It also allowed the end-users time away from their daily duties in order to attend the training. This point cannot be undervalued. The actual implantation of the Jython API and creating proof-of-concept dynamic behaviors was a grass-roots effort that a couple of developers took upon themselves. However, the actual implementation into the workforce could not have happened if not for management support.

And, equally important is continual support for the users. Even if we created the most comprehensive user-docs and provided the best training possible, this effort would die in weeks if the developers did not continue to provide support. Because our user base is not made up of seasoned programmers, a lot of hand-holding is required. Sometimes that support comes as basic as how to compare a returned object to a string value and other efforts required weeks of work to help develop complex behaviors for the analyst. In these cases the goal is turn-key code that we create, but the users maintain.

The point is: a successful implementation of an open source solution at the user base level requires that we - the developers - respect the users for what their strengths are and compensate them for where their strengths are not.

| 17 | In summary: weapons, vehicles, equipment, and tactics being used by our Military are being tested with an Agent Based Model. This Model leverages the open source and object oriented power of Python to develop Dynamic and Reactive Behaviors; which are being developed by Non-Programmers. This organization successfully implemented a Python solution because: Control Access is provided to Java-based Source Code with Python Wrapper Classes, Programmers Assist the Empowered Users with: Documentation, Training, and User Support, There was upper management support. | ALATEON Take Away Military Analyst are using Python to Model Current and Future Battlefield Scenarios In an Agent Based Model Dynamic and Reactive Behaviors are being Developed with Python Non-Programmers are Developing the Complex Behaviors with Python Java-based Source Code is Encapsulated and Control Access is Provided with Python Wrapper Classes Programmers Assist the Empowered Users with Documentation, Training, and on going User Support |
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| 18 | Thank you for your time. If you have any questions, or would like so more information, please take down my contact information. I'd be happy to speak with any of you. | ALATEON Contact Information Eric Silverman Defense Contractor Dython Wargame Developer Python Wargame Developer esilverman@alatecinc.com (w) 575-679-1457 (m) 575-915-6002 ALATEC Inc A Service Disabled Veteran Owned Small Business www.alatecinc.com twitter.com/alatec_jobs |